Dynamic Programming Approach to Unit Commitment Problem for Kuwait Power Generations

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Abstract

Optimization techniques are becoming essential in the field of power systems. In this paper, two Dynamic Programming (DP) optimization methods were used to solve a large-scale problem which is known as the unit commitment problem (UCP). A sample of ten generating units that forms one power station in Kuwait was chosen to be tested. This paper aims to have a schedule with the least possible electricity production cost while meeting the hourly demand in addition to other system constraints and this is what is known as UCP. A MATLAB code was used to generate solutions for the ten-unit system. The results showed that the conventional DP method reduced the cost by 36.1% while priority DP method reduced the cost by 35%. Since the future NEWKUWAIT vision is introducing renewable energy resources to the power system, solving the UCP will be the first step towards reaching the vision.

Keywords

Unit Commitment Problem, Optimization Methods, Dynamic programming, Priority Dynamic Programming, Conventional Dynamic Programming, Unit Generation Optimization

1. Introduction

The electricity consumption worldwide is increasing with the continuous increase of the population. This huge consumption creates threats on the power systems. Speaking locally, Kuwait's electrical systems are under risk in terms of electricity shortages and blackouts (Ansari, 2013). A new investment of buying more generators to supply the current demand would be expensive. Consequently, we need to search what problems the current grid is facing and how these problems can be solved. When studying an electrical grid, the first component is the generator. The most studied problem related to generators is the unit commitment problem (UCP) (Hobbs, Rothkopf, O'eill, & Chao, 2002). Therefore, the problem addressed in this paper is the UCP which is the scheduling of generators to produce enough electricity to meet the increasing power demands with the least possible production operating cost. The current system will be modeled and solved by knowing the inputs and the costs of the generation, and by adding the amount of consumption over time to balance the input and output. There are many techniques that can be used to solve the UCP. One of the disadvantages of the methods of solution is that the optimum solution is not guaranteed 100 percent; however, the optimality percentage varies from one method to the other (Tung, Bhadoria, Kaur, Bhadauria & Pg, 2012). Dynamic programming (DP) approach was considered in this paper. The advantage behind using DP is the easy implementation of the problem. DP includes various features that deal with controlling the size of the problem effectively (Alshareef & Saber, 2012). It was proven to be a successful technique in solving a medium size power plant. Solving unit commitment problem is an important issue which is targeted by most electrical companies and ministries. Solving such problem will help in reducing the total operating cost, as well as the emissions that are given off by fuel combustion (Taha, 2010). The main objectives of this paper are to formulate and optimize the problem, create a 24 hour schedule for ten generators that are located in Sabiya-Kuwait power system, and finally specifying when to turn them on/off to reduce the generating cost while meeting the daily demand and the operational constraints. Reaching the objectives will show the impact of this paper towards engineering solution economically in Kuwait as well as meet future environmental needs.

2. Background of the Problem

The unit commitment schedule can be daily, weekly or monthly prepared to optimize the amount of electricity generated with least cost possible (Sivanagaraju & Sreenivasan, 2010). Therefore, the problem is to generate daily electricity schedules and introduce them to Kuwait for the first time that will help in reaching the future NEWKUWAIT vision.

The directly related facility to the paper is the ministry of the electricity and water (MEW) and specifically the National Control Center (NCC) as it manages electricity and water production to fulfill Kuwait's daily demand. It was found that the generating units in all power stations are committed to be online 24/7 as it is easier to keep up with the hourly changing electricity demand. Consequently, extremely high costs are spent on excess electricity that is higher than the required demand in some hours throughout the day.

Throughout the years the electricity consumption in Kuwait has been increasing tremendously. Figure 1 illustrates the development of power stations installed capacity from 1965 up until 2015. It proves that the consumption is increasing enormously which led the country to add more generating units to satisfy the needs.

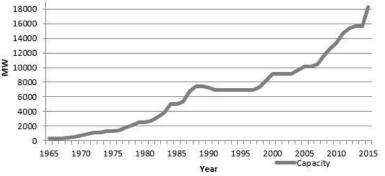


Figure 1: Development of power station installed capacity through 1965 to 2015

Figure 2 supports the information by showing the clear increase in the maximum consumption of electricity during 1996-2016 with the average increase of 4.8% per year. To keep up with this rapid increase, the government is increasing the number of units and their capacities each year which is very costly (Statistics Dept. & Information Center, 2015). When comparing figure 1 and 2, it is easily noticed that the total capacity installed by the ministry of electricity exceeds the demand needed. From here arises the importance of optimizing the generators' behavior to decrease the extra production and therefore the total cost. Kuwait's electrical grid consists of 8 power stations distributed throughout the country. The power stations are composed of different units, stream turbines, gas turbines and combined cycles with a total number of 90 units. The 8 power stations are in Shuwaikh, Shuaiba North, Shuaiba South, Doha East, Doha West, Al-Zour South, Al-Zour North, and Sabiya. To keep up with the increasing demand, the ministry kept increasing the capacity and the number of stations each year. The new introduced Unit Commitment schedule will limit the increase in generating units and reduce operation costs as well.

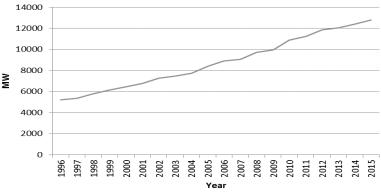


Figure 2: Maximum electricity consumption during (1996-2016)

3. Dynamic Programming Approach

Dynamic programming (DP), also known as dynamic optimization, is a method used to solve complex problems by breaking it into steps (stages). The searching process could be either in a forward direction or backward direction, meaning that the search for a solution can start at the very beginning of the system or at the very end of the system (Sen & Kothari, 1998). A study by Thakur and Titare, (2016) shows the mechanism of dynamic approach step by step. The first step is to consider two units randomly. Then, the output of the two units should be found as discrete load levels and the best combination for all levels of those units. After that, construct a cost curve for the two units and add an additional unit. Finally, calculate the cost curve for the three. This process of adding units will keep repeating until all units are taken into consideration.

3.1 Conventional Dynamic Programming

The conventional dynamic programming obtains the optimum (close to the best) solution but it requires huge memory and consumes a lot of time to get the desired solution (Moores, 1988). The total number of paths tested depends on the number of processed units and the time horizon. Since a sample of 10 units will be processes for 24 hours, paths can be calculated according to Singhal and Sharma (2011) as follows where i represents number of generating units and t is the hours needed to create the schedule:

Total number of combinations computed: $(2^i - 1) x t = (2^{10} - 1) x 24 = 1.72589 x 10^{72}$ combinations

Since the number of paths or combinations is high, another alternative method was considered to find schedules in much less time, which is the Priority Dynamic Programming.

3.2 Priority Dynamic Programming

This method is also called sequential dynamic programming since it works step by step to the final solution. This technique starts with the first unit and compares it to the next one in a strict method, and then it prioritizes the best one and continues until reaching the best schedule hourly (Singhal & Sharma, 2011). The main advantage behind using priority dynamic programming is that it reduces the dimensionality of the problem (number of paths used), as well it produces a schedule for the units at given certain time (Snyder, Powell, & Rayburn, 1987). The expected number of paths for the same previous sample size is "i" combinations hourly. As a result, only 240 combinations are tested for 10 units. Finally, this method is tested as a second scenario and the least-cost method is chosen. By that, it is guaranteed that the design is good.

4. Formulation of the Problem

Since our problem is optimization, the variables along with the objective function and constraints must be decided at the beginning in order to make sure that the problem is ready to be optimized (Salam, 2007). The objective function is minimizing the operating costs by reducing fuel costs, units starting up costs as well as shutting down costs (Wood & Wollenberg, 1996). The objective function can be represented in equation (1): where TPC is the total production cost, FC is the fuel cost, SUC is the startup cost and SDC is the total shut down cost

$$min TPC = FC + SUC + SDC \quad (1)$$

- **The Fuel cost (FC):** Fuel consumption increases in a quadratic (non-linear) form depending on the amount of power produced. FC_i is the fuel cost of unit i, Pit is the amount of power (MW) generated form unit i at time t and the coefficients a, b and c are cost coefficients for generator I in equation (2).

$$FC_i(P_{it}) = a_i + b_i P_{it} + c_i (P_{it})^2$$
 (2)

- **Start-up cost (SUC):** is the cost of turning on the offline units (Dhifaoui, Guesmi, & Abdallah, 2014). The units must be online for a minimum time before it can be turned off (minimum up time). How to calculate it is seen in equation (3).

SUC = Sum of startup costs for all units × status of the units (on/off)

$$SUC = \sum_{t=1}^{T} \sum_{i=1}^{N} SUC_{it} \times U_{it} \qquad (3)$$

- **Shutdown cost (SDC):** is the cost of turning off the online units. The minimum time required for the unit to stay online before it is switched off (minimum up time) should be considered as well.

$$SDC = \sum_{t=1}^{T} \sum_{i=1}^{N} SDC_{it} \times U_{it} (4)$$

Two different types of variables are considered in the unit commitment problem: binary and continuous. The binary variable is the status of the unit and it can either be 0 (off) or 1 (on). The continuous variable is the amount of power produced at a certain time (Yang, 2007. Both variables can be expressed as follows:

- U_{it} : The status of unit i at time t.
- *P_{it}*: The power produced in MW from unit i at time t.

To solve the unit commitment problem, many constraints should be considered such as: Load/Generation Balance: It is the total demand of electricity (D) when equal to the total generators' electricity production. Equation (5) satisfies the generation balance constraint.

$$D = \sum_{i=1}^{N} (P_{it} \cdot u(t))$$
 (5)

- **Spinning Reserve:** is defined as the extra capacity of all units in power generators that can be generated to meet the demand and keep frequency from dropping in case of emergencies as shown in equation (6).

$$\sum (Max P_{it} \cdot U_{it})) \ge (D_t + R_t)(6)$$

- **Ramp rate:** Ramp rate is the increase or decrease in the output over time (electricity generated). It provides the power system with flexibility by ramping up and down the output, given the needed demand. (Datta, 2013)

- **Minimum up time and Minimum down time:** means that whenever a unit is online, it cannot be turned off and whenever a unit is offline it cannot be started immediately until a certain time has passed.

If the minimum up time constraint is violated, the unit stays online for the next time-period shown in equation (7).

if
$$U_{it} = 1$$
 (*online*) and $t_{i,up} < t_{up,min}$
then $U_{i,t+1} = 1$ (*stays online*) (7)

If the minimum down time constraint is violated, the unit stays offline for next time-period as shown in equation (8).

if
$$U_{it} = 0$$
 (of fline) and $t_{i \text{ down min}}$

then,
$$U_{i,t+1} = 1$$
 (stays of fline) (8)

5. Results and Discussion

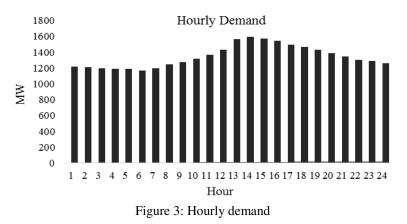
The results of the conventional dynamic programing are illustrated and tested using a prewritten MATLAB code. To solve the problem and form an hourly schedule, the first step was to collect the data required for the ten generators. Table 1 shows the data collected related to the ten generating units which include the maximum/minimum production limits in megawatts, the cold/hot startup status with their corresponding costs in Kuwaiti Dinar, and the online/offline states in hours. Each generator has its own cost coefficients which are a, b, and c.

| | Parameter | Unit 1 | Unit 2 | Unit 3 | Unit 4 | Unit 5 | Unit 6 | Unit 7 | Unit 8 | Unit 9 | Unit 10 |
|----|-----------------------|----------|---------|---------|---------|---------|---------|---------|----------|---------|---------|
| 1 | Pmin (MW) | 100 | 130 | 130 | 30 | 30 | 10 | 10 | 80 | 100 | 100 |
| 2 | Pmax (MW) | 220 | 300 | 300 | 62 | 62 | 41 | 41 | 215 | 250 | 250 |
| 3 | Cold start cost (\$) | 100 | 8000 | 8000 | 100 | 100 | 100 | 100 | 6500 | 100 | 100 |
| 4 | Min up (hr) | 1 | 5 | 5 | 1 | 1 | 1 | 1 | 4 | 1 | 1 |
| 5 | Min down (hr) | 1 | 6 | 6 | 1 | 1 | 1 | 1 | 5 | 1 | 1 |
| 6 | Initial Status (hr) | -1 | 7 | 7 | -1 | -1 | -1 | -1 | -3 | -1 | -1 |
| 7 | Hot start cost (\$) | 50 | 4000 | 4000 | 50 | 50 | 50 | 50 | 3000 | 50 | 50 |
| 8 | Cold start Hours (hr) | 0 | 5 | 5 | 0 | 0 | 0 | 0 | 3 | 0 | 0 |
| 9 | a (kd/hr) | 3242.255 | 1877.95 | 1877.95 | 3299.22 | 3299.22 | 3299.22 | 3299.22 | 3305.165 | 3299.22 | 3299.22 |
| 10 | b(kd/MW) | 48.087 | 36.043 | 36.043 | 51.269 | 51.269 | 51.269 | 51.269 | 27.675 | 51.269 | 51.269 |
| 11 | c (kd/MW^2) | 0.03326 | 0.02592 | 0.02592 | 0.27143 | 0.27143 | 0.27143 | 0.27143 | 0.10974 | 0.27143 | 0.27143 |

Table 1: Data for 10-unit system

To satisfy the demand, table 2 illustrates the demands in megawatts with their corresponding hours. The hourly demand was in July 15, 2015 as it is the peak month in consuming electricity in Kuwait (Statistics Dept. & Information Center, 2015). As mentioned before, the demand is satisfied by Sabiya power station but the problem occurs in the excess electricity wasted and extra money spent, therefore, optimization is required.

| | | 1 40 | 10 2.1 | louity | uem | anu re | <i>.</i> 1411 V | | 0-uiii | 10 | | |
|--------|------|------|--------|--------|------|--------|-----------------|------|--------|------|------|------|
| Hour | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| Demand | 1221 | 1212 | 1199 | 1191 | 1187 | 1170 | 1201 | 1250 | 1276 | 1320 | 1370 | 1430 |
| Hour | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| Demand | 1567 | 1591 | 1574 | 1546 | 1496 | 1468 | 1432 | 1389 | 1343 | 1307 | 1291 | 1258 |



As noticed from Figure 3, the demand is varying during the day with a peak in hours 13, 14 and 15 so it is predicted in these hours to have all the generating units on (or most of them).

5.1 Baseline Results

Before generating the solutions and alternatives for the problem, the current situation in Kuwait should be tested as a baseline to compare further results and check whether the system has improved or not. Kuwait's ministry of electricity and water doesn't turn off the generating units at all. To calculate the baseline all of the units should be on for the whole time interval (24 hours). The calculated baseline cost was \$ 3,642,310 (1,100,489 KWD).

5.2 Conventional Dynamic Programing Results

The first alternative solution used in this paper was the conventional dynamic programming method. After inserting the data and the equations of the UCP, a MATLAB code was used to test the program and give the results. Table 3 shows the generated hourly schedule of the ten generating units using this method. It shows that unit 1 must stay online for 24 hours without shutting it down in order to meet the demand. On the other hand, unit 6 must be turned on in hours 13:00, 14:00 and 15:00 only. This table took 946 seconds which is approximately 15.7 minutes to be constructed by the MATLAB software. The results also show that the total production cost of the generated schedule during the 24 hours is \$2,326,723 (702,947 KWD) which is much less in comparison with the baseline cost of the current state (\$3,642,310 (1,100,489 KWD)).

| | | | | | | | | | | | | Ho | urs | | | | | | | | | | | |
|---------|---|---|---|---|---|---|---|---|---|----|----|----|-----|----|----|----|----|----|----|----|----|----|----|----|
| Units | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| Unit 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 4 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 |
| Unit 5 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 |
| Unit 6 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Unit 7 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Unit 8 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 9 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 10 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

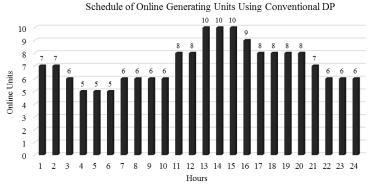
Table 3: Unit commitment schedule for conventional DP

Table 4 demonstrates the production cost of the total online generators for each hour. Adding all these costs will give us the total production cost for the 24 hours. This table was made to compare the total production cost of the scheduled units using both the conventional DP and priority DP methods.

| | I able 4: Fuel cost for each hour | | | | | | | | | | | |
|--------|-----------------------------------|--------|--------|--------|--------|--------|--------|---------|-------|-------|--------|--------|
| Hours | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| P-Cost | 92234 | 90607 | 88936 | 8545 | 85212 | 84198 | 86057 | 89104 | 90858 | 94024 | 983047 | 105308 |
| Hours | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| P-Cost | 86070 | 127732 | 125284 | 121291 | 114138 | 110248 | 105559 | 1000419 | 95806 | 93064 | 91911 | 89631 |

Table 4: Fuel cost for each hour

Consequently, Figure 4 shows the total amount of online units in each hour during the 24 hours when using conventional dynamic programming method (Snyder, Powell & Rayburn, 1987).





5.3 Priority Dynamic Programming Results

In the second alternative scenario, priority dynamic programming was used where the incremental heat rate of the generators is required. When defining the incremental heat rate, it is the total hourly change in the heat rate. The heat rate in a certain hour is the amount of fuel needed to produce I MW of electricity. Therefore, as the incremental heat rate increase, the unit will have least priority to be online (Bello, Akorede, Pouresmaeil, Ibrahim, & Ai, 2016). Prioritization of the generators is based on the incremental heat rate of each. The following Table 5 declares the heat rates used to get the results. The importance of this rate is that it is needed to be inserted as data to run the priority method on MATLAB. (Alsaffar & El-Sayed, 2014)

Table 5: Incremental heat rate for 10-units

| Units | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|-------------------------|----|----|----|----|----|----|----|----|----|----|
| Incremental Heat | 22 | 22 | 21 | 26 | 20 | 21 | 25 | 25 | 20 | 21 |
| Rate (BTU/KwH) | 22 | 23 | 21 | 20 | 29 | 51 | 33 | 23 | 20 | 21 |

Accordingly, Table 6 shows the required state of each unit for 24 hours. It is clearly noticed that more units are staying online for longer duration when comparing it to conventional DP method which satisfies the working process of Priority method.

| | | | | | | | | | | | | Ho | urs | | | | | | | | | | | |
|---------|---|---|---|---|---|---|---|---|---|----|----|----|-----|----|----|----|----|----|----|----|----|----|----|----|
| Units | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| Unit 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 4 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 5 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 6 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Unit 7 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Unit 8 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 9 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Unit 10 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Table 6: Schedule 10-units using priority DP

The detailed production cost of each hour was listed in Table 7. When comparing the table of total production cost we got from the priority method, it is clearly noticed that the conventional method gives lower production cost compared to the priority method.

| Hours | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
|--------|--------|--------|--------|--------|--------|--------|--------|---------|-------|-------|-------|--------|
| P-Cost | 92234 | 90607 | 81680 | 77709 | 77170 | 74974 | 78995 | 8380 | 86643 | 92040 | 98137 | 105408 |
| Hours | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| P-Cost | 124499 | 127732 | 125284 | 121291 | 114138 | 110248 | 105559 | 1000419 | 94751 | 90391 | 88424 | 84587 |

Table 7: Hourly production cost using priority DP

Furthermore, Figure 5 shows the overall sequence and amount of online units hourly. As a result, the total production cost resulted when applying priority dynamic programming is \$ 2,338,674 (706,588 KWD) and it took

an average of 1.45 seconds to generate the schedule which is much less than the conventional method. The detailed production cost of each hour was listed in Table 7.

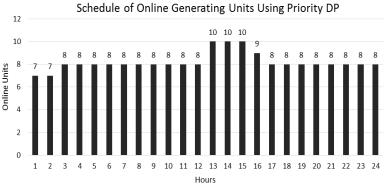


Figure 5: Schedule using Priority DP method

After testing the system and comparing the results, it was found that the best method to implement for scheduling the problem is the Conventional Dynamic Programming, since it can generate a final hourly schedule with the least possible cost compared to the baseline cost. On the other hand, this method took much longer time than the priority dynamic programming method when testing the system. This might cause some inconvenience, but since the main focus was to minimize the total cost, the time is not a big issue if there was no big time variation between the two methods. Comparing the three scenarios together, we can get the following results:

| Scenario | Total production cost (\$) | % of reduction compared to baseline | Time elapsed (sec) |
|-----------------|-------------------------------|-------------------------------------|--------------------|
| Baseline | 3,642,310 | - | - |
| Conventional DP | 2,326,723 | 36.10% | 946 |
| Priority DP | 2,338,674 | 35.70% | 1.45 |

Table 8: Comparison between results

As noticed from Table 8, conventional method reduces the operating cost of the generations by 36.1% which is a very high percentage. Putting into consideration that when the problem is solved as large scale problem (the whole power system), the cost reduction would be critical. The disadvantage of the conventional DP method is that it might consume a huge amount of time to solve such a large problem (Souroudi, 2017). For instance, 12 units were solved using conventional DP in it took more than 45 minutes to get the final schedule. In this case, the other alternative solution can be considered since the number of combinations is low. It would generate schedules fast but with higher costs than the conventional. Since the ministry of electricity and water at the current time do not pay attention that much on the costs, they might go to the priority method. However, with the continuous increase in the fuel costs, they might go to the conventional method regardless time elapsed. Finally, both methods are applicable and depending on the need of the customer (Matousek & Gärtner, 2007).

6. Conclusion

The aim of this paper is to apply optimization methods to a real-life problem which is the power system in this case. The focus was based on optimizing the generators by reducing the total production cost. Different methods were explained with their advantages and disadvantages; the discussion part of the paper included both theoretical and numerical considerations to optimize the problem. The results were translated into tables and graphs to compare the applied methods and reach the optimum solution. These tables and graphs were then explained in detail in the discussion section where economic goals were satisfied through minimizing the total production operating cost. Dynamic programming was proven to be an efficient way to solve the unit commitment problem and such a method will make a huge difference when implementing it in Gulf Cooperation Council countries in general and in Kuwait in specific. It was verified that solving the unit commitment problem is an effective, innovative and creative way in the power systems field and this paper is concluded to be successful and is able to be implemented.

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